a transport device[, comprising} having

a drive shaft rotatable around a rotational axis of said drive shaft;

drive shaft; at least two conveyors [arranged \ at said transport for devicel at least workpiece ach[, said transport device comprising], and a transport arm for each conveyor \from operatively [projecting associated with said drive shaft; said \ arms $c\lambda$ upled to operatively conveyors to move said conveyors independently of <u>each</u> other relative to said drive shaft and to have at least a radial movement component\ relative to the drive shaft rotational axis via encapsulated, \independent drives, said drives controlling closing and opening \ of said openings with movement of said conveyors relative to said drive shaft.

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Please amend claim 16 as follows:

16. (Three Times Amended) A vacuum chamber for processing at least one workpiece, comprising at least two openings defining respective opening areas for said at treating or handling least one workpiece thereat]; a transport device with a drive shaft for rotating said transport device around a rotational axis of said drive shaft; at least two conveyors [arranged at said for deviĉe the transport workpiece thereof, said transport device further comprising], and a transport arm for each conveyor <u>operatively</u> [projecting from] associated with said shaft[;said arms] and each being operatively coupled to one of conveyors move said to conveyors independently of each <u>other</u> relative to said drive shaft, said transport arms having at least a radial movement component relative to said drive shaft rotational axis via encapsulated independent drives.

Please amend Claim 30 as follows:

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30. (Amended) A vacuum with at least chamber <u>and a workpiece</u> openings transport arrangement with which at least one workpiece within the chamber is selectively brought into a position adjacent to one of said openings, whereby the transport arrangement is provided within the chamber rotatably around a rotational axis and carries at least two members for workpièce each, holding a rotation drive is \provided to rotate said workpiede transport arrangement, and at least_two

displacement drives are provided fdrm displacing said at least one workpiece each with respect to transport arrangement said members selectively brought into position aligned with one of said by rotation of transport arrangement and such position a workpiece is displaceable towards and from said opening by one of displacement drives, and said said displacement member and drives are operatively mounted on tranaport rotation drive, said displacement drive being arranged to control closing and opening of respective ones of said at least openings.

Please amend Claim 32 as follows:

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3/2. (Amended) A vacuum <u>chamber</u> comprising at least two openings respective_ opening and <u>a transport device</u> areas; operatively arranged relative to least two openings and including <u>a member</u> movable <u>relative</u> a rotational axis tb least two conveyors thereof, at transporting at <u>least</u> one workpiece each, and at least one linear drive for each of said at conveyors_ two operatively coupled between said movable member and a respective least conveyor of said at and configured conveyors linearly move salid respective conveyors relative to movable member independently from other conveyors of said at least two conveyors, said at least one linear drives being atranged to Denly

control closing and opening of said at least two openings.

Please amend Claim 33 as follows:

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JD 23. (Amended) A vacuum chamber _with_at_least_ openings and a workpiece transport arrangement with which at least one workpiece within the chamber is selectively brought into a position adjacent to one of said openings, whereby the transport arrangement is provided within the chamber rotatably around a rotational axis and carries at least one member for holding a workpiece, a rotation drive is provided to rotate said workpiece transport arrangement, and a sealed displacement drive is arranged between said transport arrangement and said at least one member for displacing a workpiece with respect to said transport arrangement, whereby said member is selectively brought into a position aligned with one of said openings by said transport rotation of arrangement and from such workpiece position a <u>displaceable towards and</u> said opening by said displacement drive, and said member and said drive displacement operatively mounted relative to said transport arrangement rotation drive, said displacement drive being further arranged to control opening and closing of said opening.

Please amend Claim 34 as follows:



(Amended) A method of processing at least one workpiece, comprising the steps of

rotating a transport device member around a rotational axis to bring the at least one workpiece adjacent an opening in a vacuum chamber having at least two openings, and

moving at least two conveyors with at least one movement component radial relative to said rotational axis, independently of each other relative to the transport device member so as selectively to move the at least one workpiece towards and away from the adjacent opening and thereby controlling opening and closing of said opening.

Please add the following claims:

35. The apparatus of claim 1, wherein said closing is a sealing closing.

36. The apparatus of claim 1, wherein, for processing at least one disk-shaped workpiece, said conveyors are configured to hold at least one of said workpieces with a predetermined positioning of a disk plane thereof, and said drive shaft arranged to move said conveyors in a direction which is offset with respect to said disk plane.

- 37. The apparatus of claim 36, wherein said offset direction is perpendicular to said disk plane.
- 38. <u>The chamber of claim</u>

 / 16, wherein said closing is a sealing closing.
 - 39. The chamber of claim 16, wherein, for processing at least one disk-shaped workpiece,

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said conveyors are configured to hold at least one of said workpieces with a predetermined positioning of a disk plane thereof, and said drive shaft arranged to move said conveyors in a direction which is offset with respect to said disk plane.

- 40. The chamber of claim 39, wherein said offset direction is perpendicular to said disk plane.
- 41. The chamber of claim 30, wherein said members are arranged to perform the closing.
- 42. The chamber of claim 30, wherein the closing is a sealing closing.
- 43. The chamber of claim 30, wherein, for processing at least one disk-shaped workpiece, said members are configured to hold at least one of said workpieces with a predetermined positioning of a disk plane thereof, and said at least one disk-shaped workpiece is arranged to be displaceable by said displacement drive in a direction which is offset with respect to said disk plane.
- 44. The chamber of claim 43, wherein said offset direction is perpendicular to said disk plane.
- 45. The chamber of claim 32, wherein the closing is a sealing closing.
- 46. The chamber of claim 32, wherein said at least one workpiece is a disk-shaped workpiece, and said at least one



linear drive has a direction which is offset with respect to a plane of said disk-shaped workpiece.

- 47. The chamber of claim 46, wherein the direction is perpendicular to said plane.
- 48. The chamber of claim 32, wherein said at least one linear drive is encapsulated within said chamber.
- 49. The chamber of claim 33, wherein the closing is a sealing closing.
- 50. The chamber of claim 33, wherein said displacement drive is a linear drive.
- 51. The chamber of claim 33, wherein, for processing at least one disk shaped workpiece, said member is configured to hold at least one of said workpieces with a predetermined positioning of a disk plane thereof, and said at least one disk-shaped workpiece is arranged to be displaceable by said displacement drive in a direction which is offset with respect to said disk plane.
- 52. The chamber of claim 51, herein said offset direction is perpendicular to said disk plane.
- 53. The method of claim 34, wherein the controlled closing is a sealing closing.
 - 54. The method of claim 34, wherein the closing and opening is performed by the conveyors.

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wherein the moving of the conveyors is in a linear direction.

wherein the moving of the conveyors is effected, for processing at least one disk-shaped workpiece in a direction which is offset to a plane of said disc-shaped workpiece.

57. The method of claim 56, wherein said direction is perpendicular to the plane.

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REMARKS

The errors noted in the Specification are corrected above, with the exception of numeral 21. We believe it is accurate to refer to the article by that numeral as well as in its more specific form, namely a storage disk. In light of the objection to the numeral 23 as designating both a bellows and grooves, applicant proposes to correct that Fig. 5 by changing numeral 23 to 22'.

The rejection of claims 1-34 under 35 U.S.C. §251 on grounds of recapture is traversed, and reconsideration is requested.

Applicant disagrees that he is attempting to recapture subject matter voluntarily surrendered in the parent application. In particular, the Office Action states that in Amendment A of the patented file, the applicant rewrote independent claim 1 to include dependent claim 9 which included dependent claim 8 as well. We would note, however, that claim 8 was not indicated to